

# Deformation Quantization in Algebraic Geometry

Amnon Yekutieli  
Ben Gurion University, ISRAEL

Lecture notes (with bibliography) at:  
[http://www.math.bgu.ac.il/  
~amyekut/lectures/def-quant.html](http://www.math.bgu.ac.il/~amyekut/lectures/def-quant.html)

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## plan

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1. What is Deformation Quantization?

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2. The Local Picture

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2. The Local Picture
3. Deforming Algebraic Varieties

# 1 What is Deformation Quantization?

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Let  $\mathbb{K}$  be a field of characteristic 0 and let  $C$  be a commutative  $\mathbb{K}$ -algebra.

A *Poisson bracket* on  $C$  is a  $\mathbb{K}$ -bilinear function

$$\{-, -\} : C \times C \rightarrow C$$

which makes  $C$  into a Lie algebra, and is a bi-derivation (i.e. a derivation in each argument).



## What is Deformation Quantization?

Let  $\mathcal{T}_C = \text{Der}_{\mathbb{K}}(C)$  be the module of derivations of  $C$ . Given  $\alpha \in \Lambda_C^2 \mathcal{T}_C$  we can define a bi-derivation  $\{-, -\}_\alpha$  by

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If  $\{-, -\}_\alpha$  is a Poisson bracket on  $C$  (i.e. the Jacobi identity holds) then we call  $\alpha$  a *Poisson structure*.

## What is Deformation Quantization?

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**Example 1.** Classical Hamiltonian mechanics. Here  $\mathbb{K} = \mathbb{R}$ ,  $X$  is an even dimensional differentiable manifold (the phase space; often  $X = T^*Y$ , the cotangent bundle of a manifold  $Y$ ) and  $C := C^\infty(X)$ , the ring of differentiable  $\mathbb{R}$ -valued functions. See [GS].

## What is Deformation Quantization?

**Example 2.** Lie theory: let  $\mathfrak{g}$  be a finite dimensional Lie algebra. Then  $C := \text{Sym } \mathfrak{g}$  can be identified with  $\mathcal{O}(\mathfrak{g}^*)$ , the ring of algebraic functions on the dual  $\mathfrak{g}^*$ . There is an intrinsically defined Poisson bracket called the Kostant - Kirillov bracket.

## What is Deformation Quantization?

**Example 3.** Here is an explicit formula.

Take  $n = 2m$  and  $C := \mathbb{K}[t_1, \dots, t_n]$ , the polynomial algebra.

Then

$$\alpha := \sum_{i=1}^m \frac{\partial}{\partial t_i} \wedge \frac{\partial}{\partial t_{i+m}}$$

is a Poisson structure on  $C$ .

## What is Deformation Quantization?

### Example 4.

Let  $\hbar$  denote a central variable (the “Planck constant”).

Suppose  $A$  is a flat  $\mathbb{K}[[\hbar]]$ -algebra with multiplication  $\star$ , and

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Given  $f, g \in C$  choose arbitrary lifts  $\tilde{f}, \tilde{g} \in A$ , and define

$$\{f, g\}_\star := \psi\left(\frac{1}{2\hbar}(\tilde{f} \star \tilde{g} - \tilde{g} \star \tilde{f})\right).$$

This makes sense because  $\hbar$  divides  $\tilde{f} \star \tilde{g} - \tilde{g} \star \tilde{f}$  in  $A$ .



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The element  $\{f, g\}_\star \in C$  turns out to be independent of the choice of lifts, and this is a Poisson bracket.

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**Definition 5.** A **deformation quantization** of  $C$  is a  $\mathbb{K}[[\hbar]]$ -bilinear associative multiplication  $\star$  on the  $\mathbb{K}[[\hbar]]$ -module  $C[[\hbar]]$ , of the form

$$f \star g = fg + \sum_{j=1}^{\infty} \beta_j(f, g) \hbar^j$$

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for  $g, f \in C$ , where

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are bi-differential operators. The multiplication  $\star$  is called a **star product**.

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**Definition 6.** Given a Poisson structure  $\alpha$  on the algebra  $C$ , a **deformation quantization of the Poisson algebra  $(C, \alpha)$**  is a deformation quantization  $\star$  of  $C$  such that

$$\{f, g\}_\star = \{f, g\}_\alpha$$

for all  $f, g \in C$ .

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The general case, i.e.  $C = C^\infty(X)$  for a Poisson manifold  $X$ , was solved by Kontsevich in 1997 [Ko1]. See the survey articles [Ke] and [CI].

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Two star products  $\star$  and  $\star'$  on  $C[[\hbar]]$  are called gauge equivalent if

$$\gamma(f \star' g) = \gamma(f) \star \gamma(g)$$

for some gauge equivalence  $\gamma$ .

## What is Deformation Quantization?

A **formal Poisson structure** on  $C$  is a series  $\alpha = \sum_{j=1}^{\infty} \alpha_j \hbar^j$ , with  $\alpha_j \in \Lambda_C^2 \mathcal{I}_C$ , which is a Poisson structure on the commutative algebra  $C[[\hbar]]$ .

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There is a similar notion of gauge equivalence of formal Poisson structures.

**Example 7.** If  $\alpha_1$  is a Poisson structure on  $C$  then  $\alpha := \alpha_1 \hbar$  is a formal Poisson structure.



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Then there is a canonical bijection*

$$Q : \frac{\{\text{formal Poisson structures on } C\}}{\text{gauge equivalence}} \xrightarrow{\cong} \frac{\{\text{deformation quantizations of } C\}}{\text{gauge equivalence}}$$

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The function  $Q$  is called the *quantization map*.

## What is Deformation Quantization?

By “preserving first order terms” I mean that given a formal Poisson structure  $\alpha = \sum_{j=1}^{\infty} \alpha_j \hbar^j$ , and corresponding deformation quantization  $\star = Q(\alpha)$ , one has

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The proof has a local aspect, which I will explain next. The global part of the proof uses formal geometry, and I will talk about it later, in the context of algebraic geometry.

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- (i)  $C = \mathcal{O}(U)$ , the coordinate ring of some affine Zariski open set  $U \subset \mathbf{A}_{\mathbb{K}}^n = \text{Spec } \mathbb{K}[t_1, \dots, t_n]$ .

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- (iii)  $\mathbb{K} = \mathbb{R}$ , and  $C = C^\infty(U)$ , the ring of differentiable functions on some open set  $U \subset \mathbb{R}^n$  (in the classical topology), with coordinates  $t_1, \dots, t_n$ .

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It is crucial that  $C$  is equipped with coordinates.

## The Local Picture

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A DG (differential graded) Lie algebra is a graded  $\mathbb{K}$ -module  $\mathfrak{g} = \bigoplus_{i \in \mathbb{Z}} \mathfrak{g}^i$ , with a bracket  $[-, -]$  satisfying the graded version of the Lie algebra identities, together with a differential  $d : \mathfrak{g}^i \rightarrow \mathfrak{g}^{i+1}$  compatible with  $[-, -]$ .

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Given a DG Lie algebra  $\mathfrak{g}$ , let us define a new DG Lie algebra

$$\mathfrak{g}[[\hbar]]^+ := \bigoplus_i \hbar \mathfrak{g}^i[[\hbar]] \subset \bigoplus_i \mathfrak{g}^i[[\hbar]],$$

in which  $\hbar$  is central.

## The Local Picture

The Maurer-Cartan equation in  $\mathfrak{g}[[\hbar]]^+$  is

$$d(\alpha) + \frac{1}{2}[\alpha, \alpha] = 0$$

for

$$\alpha = \sum_{j=1}^{\infty} \alpha_j \hbar^j \in \mathfrak{g}^1[[\hbar]]^+.$$



## The Local Picture

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One defines

$$\text{MC}(\mathfrak{g}[[\hbar]]^+) := \frac{\{\text{solutions of MC equation in } \mathfrak{g}[[\hbar]]^+\}}{\text{gauge equivalences}}.$$

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Let us return to our deformation problem, where  $C$  is one of the commutative  $\mathbb{K}$ -algebras (i)-(iii) above.

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Recall the module of derivations  $\mathcal{T}_C$ . For  $i \geq -1$  define

$$\mathcal{T}_{\text{poly}}^i(C) := \bigwedge_C^{i+1} \mathcal{T}_C.$$

So  $\mathcal{T}_{\text{poly}}^{-1}(C) = C$  and  $\mathcal{T}_{\text{poly}}^0(C) = \mathcal{T}_C$ .

## The Local Picture

The direct sum

$$\mathcal{T}_{\text{poly}}(C) := \bigoplus_i \mathcal{T}_{\text{poly}}^i(C)$$

is a DG Lie algebra, called the algebra of **poly derivations** of  $C$ . The Lie bracket is the Schouten-Nijenhuis bracket, and the differential is 0.

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The solutions of the Maurer-Cartan equation in  $\mathcal{T}_{\text{poly}}(C)[[\hbar]]^+$  are precisely the formal Poisson structures on  $C$ .



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A solution  $\beta = \sum_{j=1}^{\infty} \beta_j \hbar^j$  of the Maurer-Cartan equation in  $\mathcal{D}_{\text{poly}}(C)[[\hbar]]^+$  is a deformation quantization of  $C$ ,

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$$f \star g := fg + \sum_{j=1}^{\infty} \beta_j(f, g) \hbar^j$$

is an associative deformation of the multiplication of  $C$ .

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given by

$$\begin{aligned} \mathcal{U}_1(\partial_1 \wedge \cdots \wedge \partial_k)(f_1, \dots, f_k) := \\ \frac{1}{k!} \sum_{\sigma \in S_k} \text{sgn}(\sigma) \partial_{\sigma(1)}(f_1) \cdots \partial_{\sigma(k)}(f_k) \end{aligned}$$

for  $f_i \in C$  and  $\partial_i \in \mathcal{T}_C$ .



## The Local Picture

It is known that  $\mathcal{U}_1$  is a quasi-isomorphism – see [Ko1] for the case  $C = C^\infty(U)$ , and [Ye1] for the case  $C = \mathcal{O}(U)$  – and it induces an isomorphism of graded Lie algebras in cohomology.

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But  $\mathcal{U}_1$  is not a DG Lie algebra homomorphism!

## The Local Picture

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*Then  $\mathcal{U}_1$  extends to an  $L_\infty$  quasi-isomorphism*

$$\mathcal{U} = \{\mathcal{U}_j\}_{j=1}^{\infty} : \mathcal{T}_{\text{poly}}(C) \rightarrow \mathcal{D}_{\text{poly}}(C).$$

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*In other words,  $\mathcal{U}_1$  is a DG Lie algebra quasi-isomorphism, up to specified higher homotopies  $\mathcal{U}_2, \mathcal{U}_3, \dots$*

*Moreover, each of the maps  $\mathcal{U}_j$  is invariant under linear change of coordinates.*

## The Local Picture

There is an induced  $L_\infty$  quasi-isomorphism

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There is an induced  $L_\infty$  quasi-isomorphism

$$\mathcal{U} : \mathcal{T}_{\text{poly}}(C)[[\hbar]]^+ \rightarrow \mathcal{D}_{\text{poly}}(C)[[\hbar]]^+.$$

A calculation shows that we get a bijection

$$\begin{aligned} \text{MC}(\mathcal{U}) : \text{MC}(\mathcal{T}_{\text{poly}}(C)[[\hbar]]^+) \\ \xrightarrow{\cong} \text{MC}(\mathcal{D}_{\text{poly}}(C)[[\hbar]]^+) \end{aligned}$$

with an explicit formula.

## The Local Picture

Therefore:

**Corollary 10.** *Assume  $\mathbb{R} \subset \mathbb{K}$ . In each of the cases (i) - (iii) above there is a canonical bijection of sets*

$$Q : \frac{\{\text{formal Poisson structures on } C\}}{\text{gauge equivalence}} \xrightarrow{\cong} \frac{\{\text{deformation quantizations of } C\}}{\text{gauge equivalence}}$$

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A Poisson structure on  $X$  is an element  $\alpha \in \Gamma(X, \wedge_{\mathcal{O}_X}^2 \mathcal{T}_X)$  such that the bi-derivation  $\{-, -\}_\alpha$  is a Poisson bracket on the sheaf of functions  $\mathcal{O}_X$ .

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A Poisson structure on  $X$  is an element  $\alpha \in \Gamma(X, \wedge_{\mathcal{O}_X}^2 \mathcal{T}_X)$  such that the bi-derivation  $\{-, -\}_\alpha$  is a Poisson bracket on the sheaf of functions  $\mathcal{O}_X$ .

The aim is to deform the sheaf  $\mathcal{O}_X$ .

## Deforming Algebraic Varieties

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such that the formula

$$f \star g := fg + \sum_{j=1}^{\infty} \beta_j(f, g) \hbar^j,$$

for local sections  $f, g \in \mathcal{O}_X$ , defines an associative  $\mathbb{K}[[\hbar]]$ -algebra structure on the sheaf  $\mathcal{O}_X[[\hbar]]$ .



## Deforming Algebraic Varieties

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Recall that  $X$  is called  *$\mathcal{D}$ -affine* if  $H^i(X, \mathcal{M}) = 0$  for any quasi-coherent left  $\mathcal{D}_X$ -module  $\mathcal{M}$  and any  $i > 0$ .

## Deforming Algebraic Varieties

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*The function  $Q$  preserves first order terms, and respects étale morphisms  $X' \rightarrow X$ . If  $X$  is affine then  $Q$  is bijective. There is an explicit formula for  $Q$ .*



## Deforming Algebraic Varieties

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1. **Affine varieties.** Note that if  $X = \text{Spec } C$  is affine, but does not admit an étale morphism to  $\mathbb{A}_{\mathbb{K}}^n$ , then this result is not trivial, since there has to be some gluing. Cf. case (i) earlier.

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2. The **flag varieties**  $X = G/P$ , where  $G$  is a connected reductive algebraic group and  $P$  is a parabolic subgroup. By the Beilinson-Bernstein Theorem the variety  $X$  is  $\mathcal{D}$ -affine. This class of varieties includes the projective spaces  $\mathbb{P}_{\mathbb{K}}^n$ .

## Deforming Algebraic Varieties

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The universal Taylor expansion is a canonical embedding of algebras

$$\pi^{-1} \mathcal{O}_X \subset \mathcal{O}_{\text{Coor } X}[[\mathbf{t}]].$$

Due to the Formality Theorem we obtain an  $L_\infty$  quasi-isomorphism

$$\mathcal{U} : \mathcal{O}_{\text{Coor } X} \hat{\otimes} \mathcal{T}_{\text{poly}}(\mathbb{K}[[\mathbf{t}]]) \rightarrow \mathcal{O}_{\text{Coor } X} \hat{\otimes} \mathcal{D}_{\text{poly}}(\mathbb{K}[[\mathbf{t}]])$$

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If we had a section  $\sigma : X \rightarrow \text{Coor } X$  then we could pull  $\mathcal{U}$  down to an  $L_\infty$  quasi-isomorphism

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of sheaves of DG Lie algebras on  $X$ .

However usually **there are no global sections of  $\text{Coor } X$ .**

## Deforming Algebraic Varieties

Now the group  $GL_n$  acts on  $\text{Coor } X$  by linear change of coordinates. Let us define  $\text{LCC } X$  to be the quotient bundle  $\text{Coor } X / GL_n$ .

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**But this is not the case in algebraic geometry.** (Here is where our work diverges from that of Kontsevich.) So we must use a trick.

## Deforming Algebraic Varieties

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Using an averaging process for unipotent group actions [Ye3], for any  $i_0, \dots, i_q$  we then obtain a morphism

$$\sigma_{(i_0, \dots, i_q)} : \Delta_{\mathbb{K}}^q \times (U_{i_0} \cap \dots \cap U_{i_q}) \rightarrow \text{LCC } X.$$

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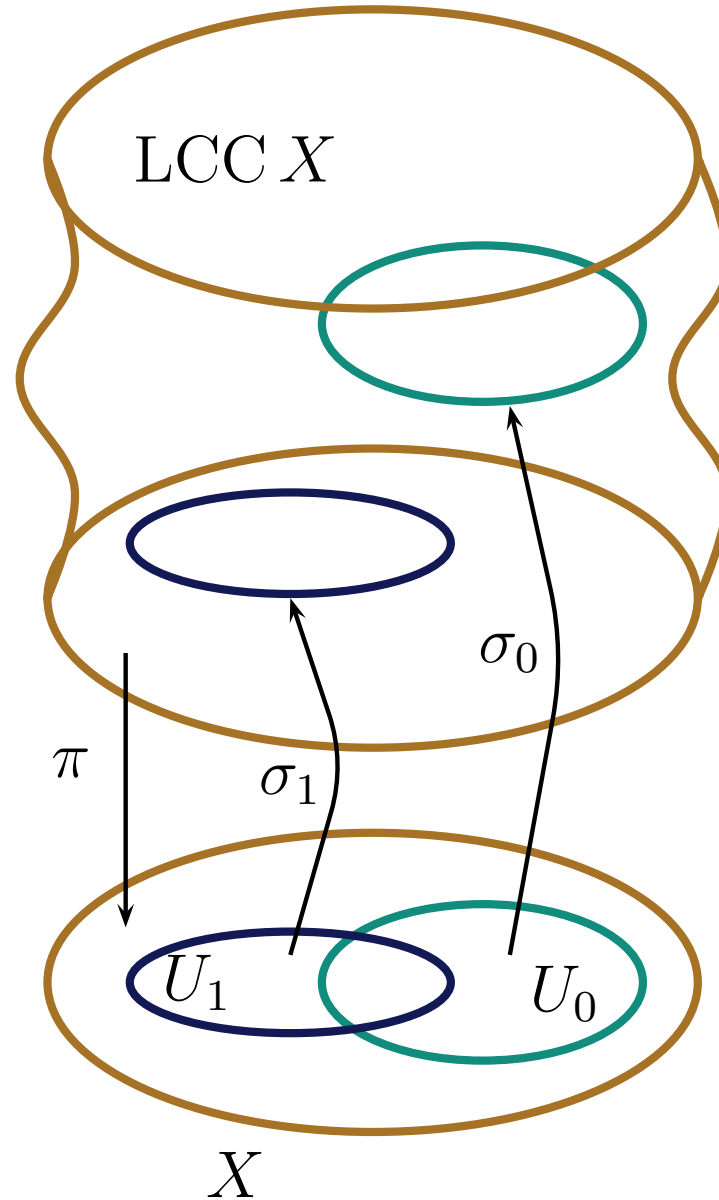
$$\sigma_{(i_0, \dots, i_q)} : \Delta_{\mathbb{K}}^q \times (U_{i_0} \cap \dots \cap U_{i_q}) \rightarrow \text{LCC } X.$$

As  $q$  varies we have a simplicial section  $\sigma$ , i.e. the simplicial relations are satisfied.

## Deforming Algebraic Varieties

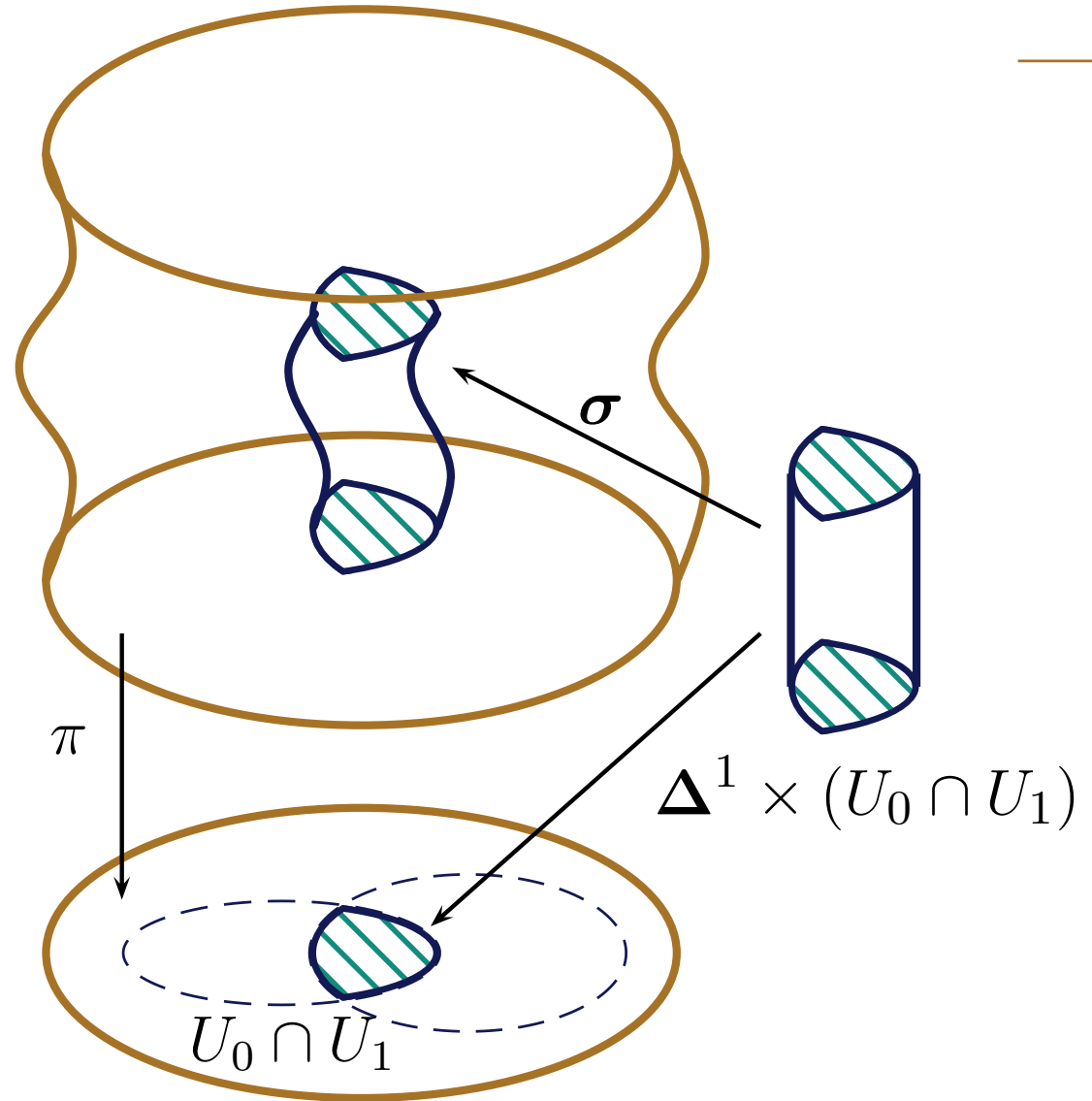
Here is an illustration  
of the case  $q = 1$ .  
We start with sections over  
two open sets

$$\sigma_i : U_i \rightarrow \text{LCC } X$$



## Deforming Algebraic Varieties

and we pass to a simplicial section  $\sigma_{(0,1)}$  interpolating between them



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The simplicial section  $\sigma$  gives rise to an  **$L_\infty$  quasi-isomorphism**

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It is now pretty easy to deduce Theorem 12, including the cohomological conditions.

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– end –



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