

# On Definability of Types in Dependent Theories

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# $\varphi$ -Types

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## Definition.

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## Example.

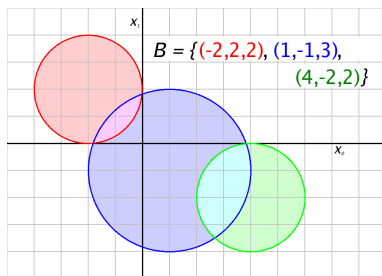
Consider  $T = \text{Th}(\mathbb{R}; +, \cdot, <, 0, 1)$  and let

$$\varphi(x_0, x_1; y_0, y_1, y_2) = [(x_0 - y_0)^2 + (x_1 - y_1)^2 \leq y_2^2].$$

A set  $B \subseteq \mathbb{R}^3$  gives a list of parameters corresponding to closed disks in  $\mathbb{R}^2$ . A  $\varphi$ -type over  $B$  is a consistent region of  $\mathbb{R}^2$  carved out by the disks.

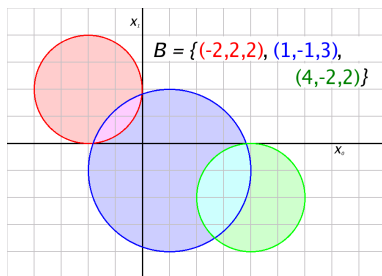
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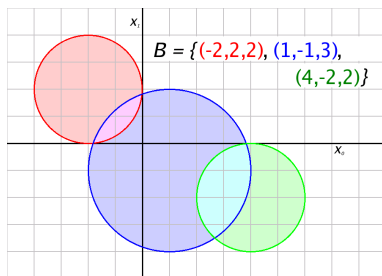


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## Definition.

The  $\varphi$ -**Stone Space** over  $B$ , denoted  $S_\varphi(B)$ , is the set of all  $\varphi$ -types over  $B$ .

# Stability and Dependence

## Definition.

We say a partitioned formula  $\varphi(\bar{x}; \bar{y})$  is **stable** if there do not exist  $\langle \bar{a}_i : i < \omega \rangle$  and  $\langle \bar{b}_j : j < \omega \rangle$  such that, for all  $i, j < \omega$

$$\models \varphi(\bar{a}_i; \bar{b}_j) \text{ if and only if } i < j.$$

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## Definition.

We say a partitioned formula  $\varphi(\bar{x}; \bar{y})$  is **dependent** (or sometimes **NIP**) if there do not exist  $\langle \bar{a}_s : s \in \mathcal{P}(\omega) \rangle$  and  $\langle \bar{b}_j : j < \omega \rangle$  such that, for all  $s \in \mathcal{P}(\omega), j < \omega$

$$\models \varphi(\bar{a}_s; \bar{b}_j) \text{ if and only if } j \in s.$$

# Stable vs. Dependent

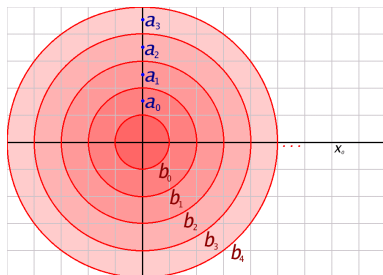
Let  $\varphi(x_0, x_1; y_0, y_1, y_2) = [(x_0 - y_0)^2 + (x_1 - y_1)^2 \leq y_2^2]$  as before.

Then  $\varphi$  is not stable. For example, take  $\bar{b}_j = (0, 0, j + 1)$  for  $j < \omega$  and  $\bar{a}_i = (0, i + 3/2)$  for  $i < \omega$ .

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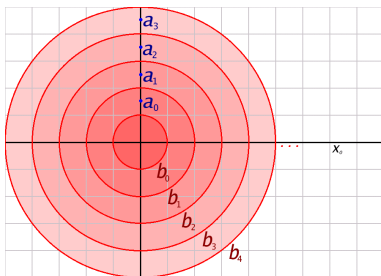
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However,  $\varphi$  is dependent. In fact, all formulas in  $\text{Th}(\mathbb{R}; +, \cdot, <, 0, 1)$  are dependent.

# Examples of Stable and Dependent Theories

## Examples.

The following theories are stable:

- 1 The theory of a vector space over a field.
- 2  $\text{Th}(\mathbb{C}; +, \cdot, 0, 1)$ .
- 3 The theory of differentially closed fields.

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## Examples.

The following theories are unstable and dependent:

- 1  $\text{Th}(\mathbb{R}; +, \cdot, <, 0, 1)$ .
- 2  $\text{Th}(\mathbb{Q}; <)$ .
- 3  $\text{Th}(\mathbb{Z}; <, +)$ .



# Definability of Types

## Definition.

Fix a formula  $\varphi(\bar{x}; \bar{y})$ , a  $\varphi$ -type  $p$ , and a formula  $\psi(\bar{y})$  defined over  $\text{dom}(p)$ . We say that  $\psi$  **defines**  $p$  if, for all  $\bar{b} \in \text{dom}(p)$ , we have that

$$\varphi(\bar{x}; \bar{b}) \in p(\bar{x}) \text{ if and only if } \models \psi(\bar{b}).$$

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## Definition.

We say that  $\varphi$  has **uniform definability of types** if there exists a finite number of  $\emptyset$ -definable formulas  $\psi_k(\bar{y}; \bar{z}_1, \dots, \bar{z}_n)$  for  $k = 1, \dots, K$  such that, for all non-empty sets  $B \subseteq \mathfrak{C}^{\text{lg}(\bar{y})}$  and  $\varphi$ -types  $p \in S_\varphi(B)$ , there exists  $\bar{c}_1, \dots, \bar{c}_n \in B$  and  $k_0 \in \{1, \dots, K\}$  such that

$$\psi_{k_0}(\bar{y}; \bar{c}_1, \dots, \bar{c}_n) \text{ defines } p.$$

# Definability of Types for Stable Formulas

## Theorem (Shelah).

The following are equivalent for a partitioned formula  $\varphi(\bar{x}; \bar{y})$ :

- 1  $\varphi$  is stable.
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**Goal:** Generalize this to dependent formulas.

# Stable Theories Have...

Definability of types has many consequences for stable theories, including the following:

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Definability of types has many consequences for stable theories, including the following:

- 1 (local type space bounds) For any  $\varphi(\bar{x}; \bar{y})$  and any infinite  $B \subseteq \mathfrak{C}^{\text{lg}(\bar{y})}$ ,  $|S_\varphi(B)| \leq |B|$ .
- 2 ( $\lambda$ -stability) There exists  $\lambda$  such that, for all  $B$  with  $|B| \leq \lambda$ ,  $|S_1(B)| \leq \lambda$ .
- 3 (stable embeddedness) For any  $B$ , every externally definable subset  $C \subseteq B$  is definable with parameters in  $B$ .
- 4 (non-forking extensions) For any type  $p$  and any  $B \supseteq \text{dom}(p)$ , there exists a non-forking extension  $q \in S(B)$  of  $p$ .
- 5 etc.

# Counting Type Spaces

Corollary.

If  $\varphi(\bar{x}; \bar{y})$  is stable, then there exists  $K, n < \omega$  such that, for any non-empty set  $B \subseteq \mathfrak{C}^{\text{lg}(\bar{y})}$ ,  $|S_\varphi(B)| \leq K \cdot |B|^n$ .

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## Theorem (Sauer's Lemma).

If  $\varphi(\bar{x}; \bar{y})$  is dependent, then there exists  $K, n < \omega$  such that, for any non-empty **FINITE** set  $B \subseteq \mathfrak{C}^{\text{lg}(\bar{y})}$ ,  $|S_\varphi(B)| \leq K \cdot |B|^n$ .



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## Definition.

We say that a dependent formula  $\varphi$  has **VC-density**  $\ell$  if  $\ell$  is the infimum of all  $n \in \mathbb{R}_+$  such that the condition in the above theorem holds.

# Definability of Types over Finite Sets

For any formula  $\varphi(\bar{x}; \bar{y})$  and any  $\varphi$ -type  $p$  with a finite domain,  $p$  is definable.

Let  $B_1 = \{\bar{b} \in \text{dom}(p) : \varphi(\bar{x}; \bar{b}) \in p(\bar{x})\}$ . Then, since  $\text{dom}(p)$  is finite,  $B_1$  is finite, so the following is a formula:

$$\psi(\bar{y}) = \left[ \bigvee_{\bar{b} \in B_1} \bar{y} = \bar{b} \right].$$

Notice that  $\psi$  defines  $p$ .

# Uniform Definability of Types over Finite Sets

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We say that  $\varphi$  has **uniform definability of types over finite sets (UDTFS)** if there exists a finite number of  $\emptyset$ -definable formulas  $\psi_k(\bar{y}; \bar{z}_1, \dots, \bar{z}_n)$  for  $k = 1, \dots, K$  such that, for all non-empty **FINITE** sets  $B \subseteq \mathcal{C}^{\text{lg}(\bar{y})}$  and  $\varphi$ -types  $p \in S_\varphi(B)$ , there exists  $\bar{c}_1, \dots, \bar{c}_n \in B$  and  $k_0 \in \{1, \dots, K\}$  such that

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# UDTFS Implies VC-Density Bound

Fact.

If  $\varphi$  has UDTFS, witnessed by  $\psi_k(\bar{y}; \bar{z}_1, \dots, \bar{z}_n)$  for  $k = 1, \dots, K$ , then  $\varphi$  has VC-density  $\leq n$ .

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Why?

For any fixed finite  $B \subseteq \mathcal{C}^{\text{lg}(\bar{y})}$ ,  $\varphi$ -types over  $B$  are determined by:

- ① elements  $\bar{c}_1, \dots, \bar{c}_n \in B$ , and
- ② some  $k_0 \in \{1, \dots, K\}$ .

So there are, at most,  $K \cdot |B|^n = K \cdot |B|^n$  such  $\varphi$ -types.

# Facts about UDTFS

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- 1 If  $\varphi(\bar{x}; \bar{y})$  is stable, then  $\varphi$  has UDTFS.
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## Theorem (Johnson, Laskowski).

If  $T$  is o-minimal, then  $T$  has UDTFS.



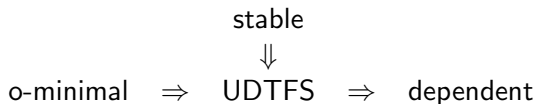
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# dp-Minimal Theories

## Definition.

A theory  $T$  is **dp-minimal** if there do not exist  $\varphi(x; \bar{y})$ ,  $\psi(x; \bar{z})$ ,  $\langle \bar{b}_i : i < \omega \rangle$ , and  $\langle \bar{c}_j : j < \omega \rangle$  such that, for all  $i_0, j_0 < \omega$ , the type

$$\{\neg\varphi(x; \bar{b}_{i_0}), \neg\psi(x; \bar{c}_{j_0})\} \cup \{\varphi(x; \bar{b}_i) : i \neq i_0\} \cup \{\psi(x; \bar{c}_j) : j \neq j_0\}.$$

is consistent.

# Examples of dp-Minimal Theories

## Examples.

The following theories are dp-minimal:

- ① Any o-minimal theory or weakly o-minimal theory,
- ②  $\text{Th}(\mathbb{Z}; <, +)$ ,
- ③  $\text{Th}(\mathbb{Q}_p; +, \cdot, |, 0, 1)$  (where  $x|y$  iff.  $v_p(x) \leq v_p(y)$ ),
- ④ Algebraically closed valued fields.
- ⑤ In general, any VC-minimal theory is dp-minimal.
- ⑥ Any theory with VC-density  $\leq 1$  is dp-minimal.

# dp-Minimal Theories have UDTFS

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If  $\varphi(\bar{x}; \bar{y})$  and  $N < \omega$  are such that, for all  $B \subseteq \mathfrak{C}^{\text{lg}(\bar{y})}$  with  $|B| = N$ ,  $|S_\varphi(B)| \leq N(N+1)/2$ , then  $\varphi$  has UDTFS (in particular if  $\varphi$  has VC-density  $< 2$ , then  $\varphi$  has UDTFS).

# Valued Fields and UDTFS

## Theorem (G.).

If  $(K, k, \Gamma)$  is a Henselian valued field that has elimination of field quantifiers in the Denef-Pas language,  $\text{Th}(k)$  has UDTFS, and  $\text{Th}(\Gamma)$  has UDTFS, then the full theory in the Denef-Pas language has UDTFS.

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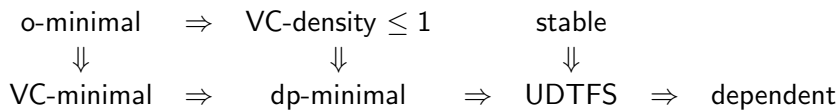
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## Examples.

The theories of the following structures in the Denef-Pas language have UDTFS:

- 1  $\mathbb{Q}_p$ ,
- 2  $\mathbb{R}((t))$ ,
- 3  $\mathbb{C}((t))$ ,
- 4  $\mathbb{C}((t^{\mathbb{Q}}))$ .

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Open Question (Laskowski).

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## More Open Questions.

- 1 Is UDTFS closed under reducts?
- 2 If  $\varphi(\bar{x}; \bar{y})$  has UDTFS, then does  $\varphi^{\text{opp}}(\bar{y}; \bar{x})$  have UDTFS?

# VC-Minimal Theories

## Definition.

A theory  $T$  is VC-minimal if there exists  $\Psi = \{\psi_i(x; \bar{y}_i) : i \in I\}$  a collection of formulas so that:

- 1 For all  $i, j \in I$ ,  $\bar{b} \in \mathfrak{C}^{\text{lg}(\bar{y}_i)}$ , and  $\bar{c} \in \mathfrak{C}^{\text{lg}(\bar{y}_j)}$ , one of the four partial types  $\{\pm\psi_i(x; \bar{b}), \pm\psi_j(x; \bar{c})\}$  is inconsistent; and
- 2 For any parameter-definable formula  $\theta(x)$ ,  $\theta$  is  $T$ -equivalent to a boolean combination of instances of  $\psi_i(x; \bar{b})$  for various  $i \in I$  and  $\bar{b} \in \mathfrak{C}^{\text{lg}(\bar{y}_i)}$ .

# Examples of VC-Minimal Theories

## Examples.

- 1 If  $T$  is o-minimal, then  $T$  is VC-minimal.
- 2 If  $T$  is strongly minimal, then  $T$  is VC-minimal.
- 3 In particular,  $\text{Th}(\mathbb{C}; +, \cdot, 0, 1)$  is VC-minimal.
- 4 The theory of algebraically closed valued fields is VC-minimal.

# The Kueker Conjecture

## Kueker Conjecture.

If  $T$  is a theory in a countable language such that every uncountable model of  $T$  is  $\aleph_0$ -saturated, then  $T$  is  $\aleph_0$ -categorical or  $\aleph_1$ -categorical.

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## Theorem (G.).

If  $T$  is VC-minimal, then  $T$  satisfies the Kueker Conjecture.

# Proof Sketch.

- First we show that a VC-minimal theory  $T$  is either stable, or interprets an infinite linear order.
- By the work of Hrushovski, if  $T$  is stable, then  $T$  satisfies the Kueker Conjecture.
- By that same paper of Hrushovski, if  $T$  interprets a linear order, then  $T$  satisfies the Kueker Conjecture.

