

# מבוא לטופולוגיה, מבחן סופי (מועד א). אוניברסיטת בן גוריון

<p>כללים: אסור לכתוב בצבע אדום. הבודק רוצה לראות רק את הגרסה הסופית של הפתרון, לא את כל נדודי הביניים. השתמשו בטיוטה לכל הנסיונות ההתחלתיים. הפתרון אמור להיות מסודר, מדויק (ולא ארוך). בזמן הבחינה מרצים/מתרגלים עונים רק על שאלות הקשורות לניסוח של הבחינה. אנחנו לא עונים על שאלות כמו: "האם זאת דרך נכונה?", "באיזה משפט צריכים להשתמש כאן?", "אני שכחתי את הנוסחה/הניסוח של...".</p>	<p>מספר הקורס: 201.1.0091 מרצה: ד.קרנר תאריך: 08.07.2016 משך הבחינה: 3 שעות ניקוד: פתרו את כל השאלות (סה"כ 105 נקודות) אין להשתמש בכל חומר עזר, לרבות מחשבוני</p>
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בכל השאלות: תשובה "כן" דורשת הוכחה/בניה מפורשת, תשובה "לא" - הסבר מפורש/דוגמא נגדית

(1) (א) (10) נגדיר קבוצה  $X \subset \mathbb{R}^2$   $X = \left\{ e^\phi \left(1 - \frac{1}{100}\right) < r < e^\phi \left(1 + \frac{1}{100}\right), \phi \in (-\infty, \infty) \right\}$ , כאן  $(r, \phi)$  קואורדינטות קוטביות. האם  $X$  (עם הטופולוגיה המושרית) הומאומרפי ל  $\mathbb{R}^2$ ?

(2) (ב) (20) יהי  $(X, d)$  מרחב קשיר מסילתית (עם לפחות שתי נקודות). הוכיחו ש  $X$  הנו גדול מכן מניה בעוצמתו.

(2) (10) תהי  $X = C[0, 1]$  קבוצת פונקציות רציפות ב  $[0, 1]$  ונגדיר  $d(f, g) = \sup_{x \in [0, 1]} |f(x) - g(x)|$  האם  $(X, d)$  הנו מרחב שלם?

(3) (א) (20) נתונות העתקות רציפות,  $\left\{ S^1 \xrightarrow{f_\alpha} \prod_{\beta \in B} S^n \right\}_{\alpha \in A}$ , כאשר  $n \in \mathbb{N}$  קבוע,  $A, B$  קבוצות אינסופיות ו  $\prod_{\beta \in B} S^n$  מרחב עם טופולוגית מכפלה. נניח שעבור כל תת-קבוצה סופית  $I \subset A$  מתקיים:  $\bigcap_{\alpha \in I} f_\alpha(S^1) \neq \emptyset$ . הוכיחו:  $\bigcap_{\alpha \in A} f_\alpha(S^1) \neq \emptyset$ .

(2) (ב) (20) יהי  $X = (0, 1]$  עם טופולוגיה רגילה. האם קיימת קומפקטיפיקצית Hausdorff  $\bar{X}$  של  $X$  שעבורה  $\bar{X} \setminus X$  הומאומרפי ל  $[0, 1]^2$ ?

(4) (א) (5) חשבו  $\pi_1(\mathbb{R}^3 \setminus (0, 0, 0))$ .

(2) (ב) חשבו  $\pi_1(\mathbb{R}^3 \setminus \{(0, 0, 1), (0, 0, -1)\})$ .

בהצלחה!

**INTRODUCTION TO TOPOLOGY,  
SKETCHY SOLUTIONS OF MOED.A, (08.07.2016)**

- (1) (a) Draw  $X \subset \mathbb{R}^2$ , in the  $x, y$  coordinates this is a neighborhood of the spiral  $\{r = e^\phi, \phi \in (-\infty, \infty)\}$ . In the  $r, \phi$  coordinates this is an infinite strip whose width tends to zero as  $\phi \rightarrow -\infty$  and tends to infinity as  $\phi \rightarrow \infty$ .

Define the map  $X \xrightarrow{f} (-1, 1) \times \mathbb{R}$  by  $f(r, \phi) = (100 \frac{r-e^\phi}{e^\phi}, \phi)$ . This map is continuous, injective and (by direct check) surjective. Its inverse is continuous as well, thus  $f$  is a homeomorphism. Finally, using  $(0, 1) \stackrel{homeo}{\approx} \mathbb{R}$  we get:  $X \stackrel{homeo}{\approx} \mathbb{R}^2$ .

- (b) Suppose  $(X, d)$  is countable, we show that  $X$  is non-connected. Fix some point  $x_0 \in X$  and a number  $r < \frac{\text{diam}(X)}{2}$  such that for any other point  $x \in X$ :  $d(x_0, x) \neq r$ . (Such  $r$  exists because  $X$  is countable.) Then the open ball  $Ball_r(x_0)$  does not contain the whole  $X$  and no points of  $X$  belong to the boundary of  $Ball_r(x_0)$ . Further, the subset  $U_{>r} = \{x \mid d(x, x_0) > r\}$  is non-empty and open. Thus we get a separation into the disjoint open subsets  $X = Ball_r(x_0) \amalg U_{>r}$ . This means  $X$  is non-connected, giving a contradiction.

Another solution. Fix any two points  $x_1, x_2 \in X$  and take a path  $\gamma$  from  $x_1, x_2$ . This is a compact subset of a metric space, in particular Hausdorff. As has been proved in a lecture: "a compact Hausdorff space with no isolated points is uncountable".

Another solution. Fix any two points  $x_1, x_2 \in X$  and take a path  $\gamma$  from  $x_1, x_2$ . Consider the function  $\gamma \xrightarrow{\text{dist}} \mathbb{R}$ , defined by  $\text{dist}(x) = d(x_1, x)$ . This function is continuous and  $\text{dist}(x_1) = 0 \neq \text{dist}(x_2)$ . Its image contains the interval  $[0, \text{dist}(x_2)] \subset \mathbb{R}$ . (Suppose  $[0, \text{dist}(x_2)] \ni c \notin \text{dist}(\gamma)$ , then  $\text{dist}^{-1}[0, c] \amalg \text{dist}^{-1}(c, \text{dist}(x_2))$  is a separation of  $\gamma$  into disjoint open subsets.) Thus  $\gamma$  must have at least a continuum of points.

- (2) Let  $\left\{ [0, 1] \xrightarrow{f_n} \mathbb{R} \right\}_n$  be a Cauchy sequence for the metric  $d$ . For each  $x \in X$  the sequence of points  $\{f_n(x) \in \mathbb{R}\}$  converges, by the completeness of  $\mathbb{R}$ . Define the function  $f$  pointwise,  $f(x) = \lim f_n(x)$ .

We claim that the convergence  $f_n \rightarrow f$  is not just pointwise, but uniform. This follows immediately by the form of the metric. Finally, as the convergence is the uniform, the limit  $f$  is a continuous function (as has been proved in Infi). Therefore  $(X, d)$  is complete.

- (3) (a) By Tychonoff's theorem the space  $\prod_{\beta \in B} S^n$  is compact in the product topology. For each  $\alpha$  the image  $f_\alpha(S^1) \subset \prod_{\beta \in B} S^n$  is a compact subset (being a continuous image of a compact space). Thus  $f_\alpha(S^1) \subset \prod_{\beta \in B} S^n$  is a closed subset. Therefore we have a collection of closed subsets,  $\{f_\alpha(S^1) \subset \prod_{\beta \in B} S^n\}_{\alpha \in A}$ , with the property of non-empty finite intersections. Thus, by compactness of  $\prod_{\beta \in B} S^n$ , the total intersection is non-empty.

- (b) We construct the needed compactification as the closure,  $\overline{\Gamma_f}$ , of the graph of a map  $X \xrightarrow{f} [0, 1]^2$ . Present  $(0, 1] = \bigcup_{n=1}^{\infty} [\frac{1}{n+1}, \frac{1}{n}]$  and define  $f$  on each  $[\frac{1}{n+1}, \frac{1}{n}]$  as the Peano curve. More precisely:  $f|_{[\frac{1}{n+1}, \frac{1}{n}]}$  is the Peano curve that begins at the point  $(n \bmod(2), 0) \in [0, 1]^2$  and ends at the point  $(n+1 \bmod(2), 0) \in [0, 1]^2$ . By the construction these maps glue to a continuous map  $X \xrightarrow{f} [0, 1]^2$ . This map is surjective on each segment  $[\frac{1}{n+1}, \frac{1}{n}]$ , therefore the set of partial limits of  $f(t)$  as  $t \rightarrow 0$  is precisely  $[0, 1]^2$ .

Finally,  $\overline{X} \subset \mathbb{R}^3$ , in particular it is Hausdorff.

Another version of  $f$ . Define the map  $(0, 1] \xrightarrow{f} [0, 1]^2$  by  $f(x) = (|\sin \frac{1}{x}|, |\sin \sqrt{\frac{1}{x}}|)$ . Check this map on the intervals  $[\frac{1}{t^2}, \frac{1}{(t+\delta)^2}]$ , as  $t \rightarrow \infty$ , while  $0 < \delta$  is small, but fixed. On each such interval the  $y_2$  coordinate changes slightly, while the  $y_1$  coordinate oscillates.

(4) We claim that in both cases all the loops are contractible and therefore  $\pi_1(\dots) = \{1\}$ .

As  $\mathbb{R}^3 \setminus \{\dots\}$  is connected, it is enough to consider the loops based at e.g.  $(1, 0, 0)$ .

(a) Apply the homotopy  $(\mathbb{R}^3 \setminus (0, 0, 0)) \times [0, 1] \xrightarrow{F(x,t)} \mathbb{R}^3 \setminus (0, 0, 0)$  defined in polar coordinates by

$$\phi(t) = \phi, \quad \theta(t) = \theta, \quad r(t) = r(1-t) + t.$$

This homotopy pushes every loop in  $\mathbb{R}^3 \setminus (0, 0, 0)$  to a loop on  $S^2$ . (Note that the base point,  $(1, 0, 0) \in S^2$ , remains fixed.) And any loop on the sphere is contractible, as has been shown in the class/homeworks.

(b) Fix some loop  $\gamma \subset \mathbb{R}^3 \setminus \{(0, 0, 1), (0, 0, -1)\}$ , defined by  $[0, 1] \xrightarrow{f} \mathbb{R}^3 \setminus \{(0, 0, 1), (0, 0, -1)\}$ ,  $f(0) = f(1) = (1, 0, 0)$ .

First we construct the homotopy that pushes-out  $\gamma$  to the cylinder  $\{x^2 + y^2 = 1\} \subset \mathbb{R}^3$ .

- If  $\gamma$  does not cross the  $\hat{z}$ -axis then the homotopy is induced by the homotopy  $\mathbb{R}^2 \setminus (0, 0) \rightsquigarrow S^1$ ,  $(r, \phi) \rightarrow (r(1-t) + t, \phi)$ .
- In the general case one considers a small punctured cylinder  $D_\epsilon^2 \times (-\infty, 0] \setminus (0, 0, -1)$  and its preimage  $f^{-1}(D_\epsilon^2 \times (-\infty, 0] \setminus (0, 0, -1))$ . The later is an open subset of  $[0, 1]$ , hence splits into the union  $\cup(a_i, b_i)$ . On each  $(a_i, b_i)$  one deforms  $f$  slightly, so that the deformed path does not cross the  $\hat{z}$ -axis. Do the same for the cylinder  $D_\epsilon^2 \times [0, \infty) \setminus (0, 0, 1)$  Then apply the homotopy as above.

Now we get a loop on the cylinder  $\partial(D_\epsilon^2) \times \mathbb{R}$ , which can be shrunk into a loop inside the circle  $\{z = 0, x^2 + y^2 = 1\} \subset \mathbb{R}^3$ .

Finally, we contract this circle to the point  $(1, 0, 0)$ .

Another version of homotopy. As  $\gamma$  does not pass through the points  $(0, 0, 1), (0, 0, -1)$  it has a positive distance from both of them. Thus take small spheres centered at each of these points and inflate them up to radius 1. This pushes any loop inside  $\mathbb{R}^3 \setminus \{(0, 0, 1), (0, 0, -1)\}$  to a loop inside

$$\mathbb{R}^3 \setminus \{Ball_1(0, 0, 1) \cup Ball_1(0, 0, -1)\}.$$

Now, if the loop passes through the point  $(0, 0, 0)$ , it can be moved off this point. After this the loop can be pushed off the ball  $Ball_1(0, 0, 0)$ . Thus we get a loop inside  $\mathbb{R}^3 \setminus Ball_1(0, 0, 0)$  and this is contractible as in part a.