

# Geometric Calculus 1, 201.1.1031

## Homework 4 Fall 2019 (D.Kerner)



- (1) Check the path-connectedness of the sets:
- $\{\sum \lambda_i x_i^{n_i} = 1\} \subset \mathbb{R}^n$  (here  $\{\lambda_i \in \mathbb{R}\}$  and  $\{n_i \in \mathbb{N}\}$  are fixed)
  - $\{x_1(\sin(x_2^3 - x_3^2) - x_4^4) = 1\} \subset \mathbb{R}^4$
- (2) Using the standard inner product on  $Mat_{m \times n}(\mathbb{R})$ ,  $\langle A, B \rangle = trace(A \cdot B^t)$ , we identify  $Mat_{m \times n}(\mathbb{R})$  with  $\mathbb{R}^{mn}$ . Thus we can define open/closed balls and open/closed/compact/bounded/path-connected subsets of  $Mat_{m \times n}(\mathbb{R})$ .
- Describe (as explicitly as possible)  $Ball_r(0)$  and the standard sphere of radius 1 in  $Mat_{2 \times 2}(\mathbb{R})$ .
  - Prove that the trace and the determinant are continuous functions,  $Mat_{n \times n}(\mathbb{R}) \rightarrow \mathbb{R}$ .
  - More generally, prove that all the coefficients of the characteristic polynomial of  $A$  depend continuously on  $A$ .
  - Consider the matrix product,  $Mat_{m \times n}(\mathbb{R}) \times Mat_{n \times k}(\mathbb{R}) \rightarrow Mat_{m \times k}(\mathbb{R})$ ,  $(A, B) \rightarrow A \cdot B$ . Prove: this is a continuous function. Prove: the inverse of a matrix,  $GL(n, \mathbb{R}) \rightarrow GL(n, \mathbb{R})$ ,  $A \rightarrow A^{-1}$ , is a continuous function.
  - Let  $SL(n, \mathbb{R}) := \{A \mid det(A) = 1\}$ ,  $O(n, \mathbb{R}) := \{A \mid A \cdot A^t = \mathbf{1}\}$ ,  $SO(n, \mathbb{R}) = O(n, \mathbb{R}) \cap SL(n, \mathbb{R})$ .  
Prove:  $O(n, \mathbb{R})$  sits inside the sphere of radius  $\sqrt{n}$  centered at  $\mathbf{0} \in Mat_{n \times n}(\mathbb{R})$ . Is  $SL(n, \mathbb{R})$  bounded?  
Which of the sets  $GL(n, \mathbb{R})$ ,  $SL(n, \mathbb{R})$ ,  $O(n, \mathbb{R})$ ,  $SO(n, \mathbb{R})$  are open/closed/compact?
  - Prove:  $O(n, \mathbb{R})$  is not path-connected. Is  $GL(n, \mathbb{R})$  path-connected?
  - Let  $X_{diag} \subset Mat_{n \times n}(\mathbb{R})$  be the subset of all the matrices that are diagonalizable over  $\mathbb{C}$ . (i.e.  $U \cdot A \cdot U^{-1}$  is diagonal for some  $U \in GL(n, \mathbb{C})$ ) Prove: any matrix whose eigenvalues are pairwise distinct complex numbers belongs to  $int(X_{diag})$ .
  - Conclude:  $\overline{X_{diag}} = Mat_{n \times n}(\mathbb{R})$  and  $int(Mat_{n \times n}(\mathbb{R}) \setminus X_{diag}) = \emptyset$ . (Because of this many engineers claim "Any matrix in real life is diagonalizable".)
  - Is  $Mat_{n \times n}(\mathbb{R}) \setminus X_{diag}$  a closed subset of  $Mat_{n \times n}(\mathbb{R})$ ? (Hint: look at  $Mat_{2 \times 2}(\mathbb{R})$ )
- (3) Define the polar coordinates in  $\mathbb{R}^n$  by  $r = \sqrt{\sum x_i^2}$ ,  $\left\{ \phi_j = \arccos \frac{x_j}{\sqrt{\sum_{i=1}^j x_i^2}} \in [0, \pi] \right\}_{j=3, \dots, n}$ , while  $\phi_2 \in [0, 2\pi)$  is determined by  $\phi_2 = \arccos \frac{x_1}{\sqrt{x_1^2 + x_2^2}} = \arcsin \frac{x_2}{\sqrt{x_1^2 + x_2^2}}$ .
- Verify that for  $n = 2, 3$  we get the ordinary polar coordinates in  $\mathbb{R}^2, \mathbb{R}^3$ . Why do we need two expressions for the angle  $\phi_2$ ?
  - Give the geometric definition of all the angles  $\phi_j$ ,  $j = 2, \dots, n$ .
  - Write the explicit formulas for the map  $(r, \underline{\phi}) \rightarrow \underline{x}$ .
  - Verify that the domain of the coordinate change  $\underline{x} \rightarrow (r, \underline{\phi})$  is  $\mathbb{R}^n \setminus \{x_1^2 + x_2^2 = 0\}$  while its image is  $\mathbb{R}_{>0} \times (0, \pi)^{n-2} \times [0, 2\pi)$ .
  - Verify that the map  $\mathbb{R}_{>0} \times (0, \pi)^{n-2} \times [0, 2\pi) \ni (r, \underline{\phi}) \rightarrow \underline{x} \in \mathbb{R}^n \setminus \{x_1^2 + x_2^2 = 0\}$  is continuous and bijective. Is its inverse continuous?
  - Using polar coordinates prove (again) that the sphere  $S^{n-1} \subset \mathbb{R}^n$  is compact and path-connected.
- (4)
- We have defined the norms  $\|\cdot\|_p$  on  $\mathbb{R}^n$ , for  $1 \leq p \leq \infty$ . Verify that these are indeed norms. Draw  $Ball_1^{\|\cdot\|_p}(0) \subset \mathbb{R}^2$ .
  - Prove:  $\lim_{p \rightarrow \infty} \|x\|_p = \|x\|_\infty$  for any  $x \in \mathbb{R}^n$ .
  - Let  $C[a, b]$  be the space of functions continuous on  $[a, b] \subset \mathbb{R}^1$ . Prove that  $\|f\|_p := \sqrt[p]{\int_a^b |f(x)|^p dx}$  defines a norm on  $C[a, b]$ , for any  $1 \leq p \leq \infty$ . (Hint: Hölder and Minkowski)
  - Prove:  $\lim_{p \rightarrow \infty} \|f\|_p = \|f\|_\infty$  for any  $f \in C[a, b]$ .
  - Let  $\|\cdot\|_1, \|\cdot\|_2$  be two equivalent norms on a vector space  $V_{\mathbb{R}}$  (not necessarily of finite dimension). Prove:
    - $S \subseteq V$  is open/closed/compact/path-connected w.r.t.  $\|\cdot\|_1$  iff it is w.r.t.  $\|\cdot\|_2$ .
    - $int^{\|\cdot\|_1} S = int^{\|\cdot\|_2} S$ ,  $\overline{S}^{\|\cdot\|_1} = \overline{S}^{\|\cdot\|_2}$ . (The interior and the closure w.r.t. these norms)
    - $V \supseteq \mathcal{D}_f \xrightarrow{f} \mathbb{R}^m$  is  $\|\cdot\|_1$ -continuous iff it is  $\|\cdot\|_2$ -continuous.
    - $(V, \|\cdot\|_1)$  is complete iff  $(V, \|\cdot\|_2)$  is complete.  $((V, \|\cdot\|)$  is complete if every Cauchy sequence converges)
  - We have skipped some steps in the proof of "All the norms are equivalent on  $\mathbb{R}^n$ ". Fill in all the details.