

Geometric Calculus 2, 201.1.1041

Homework 6

Spring 2022 (D.Kerner)

Questions to submit: 1. 2.b. 2.d. 3.a. 3.e. 4.b.iii. 4.c.ii. 4.d. 4.f.



- For a point $p \in M$ denote by $\mathfrak{m}_p \subset C^\infty(M)$ the subset of functions that vanish at p . Prove: \mathfrak{m}_p is an ideal in the ring $C^\infty(M)$. Define the map $C^\infty(M) \rightarrow T_p^*M$ by $f \rightarrow df|_p$. Prove: its kernel is \mathfrak{m}_p^2 .
- We have defined the (scalar) integral $\int_C f dC$ via partitions on C , and for these we have (slightly) used the parametrization of C . Verify: the integral (if exists) does not depend on the choice of parametrization.
 - Compute the integrals:
 - $\int_{\{x^{\frac{2}{3}}+y^{\frac{2}{3}}=a^{\frac{2}{3}}\}} (x^{\frac{4}{3}} + y^{\frac{4}{3}}) dC$.
 - $\int_{(x^2+y^2)^2=a^2(x^2-y^2)} |y| dC$.
 - For which values of $s > 0$ the planar curve defined by $r(\theta) = \frac{1}{1+\theta^s}$, $\theta \in [0, \infty)$ has a finite length?
 - A curve $C \subset \mathbb{R}^3$ is defined via parameterization in polar coordinates by equations $r = r(\phi)$, $\theta = \theta(\phi)$, for $\phi \in [\phi_0, \phi_1]$. (Here θ is the angle with \hat{z} -axis.) Prove: $\int_C f \cdot dC = \int_{\phi_0}^{\phi_1} f \cdot \sqrt{(\partial_\phi r)^2 + r^2(\partial_\phi \theta)^2 + r^2 \sin^2(\theta)} d\phi$.
 - Suppose $\int_C f dC$ exists. Prove: $|\int_C f dC| \leq \int_C |f| dC$.
- Compute $\int_C \vec{F} \cdot d\vec{C}$ in the following cases:
 - $\vec{F}(\underline{x}) = (x_1, x_2^2, \dots, x_n)$, $C = \{(\sin(t), \sin^2(t), \dots, \sin^n(t)) \mid t \in [0, \pi]\}$.
 - $\int_{\{x^2+y^2+z^2=1, y=-x, z>0\}} (z^2 dx + 3y^2 dy - x^2 dz)$, the curve begins at $(\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}, 0)$ and ends at $(\frac{-1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0)$.
 - Given a smooth curve $C \subset \mathbb{R}^n$, take the projections onto the coordinate axes $\{C \xrightarrow{\pi_i} \text{Span}(\hat{x}_i)\}$. Suppose these are diffeomorphisms onto their images. Prove: $\int_C \vec{F} \cdot \vec{C} = \sum \int_{\pi_i(C)} F_i(\pi_i^{-1}(x_i)) dx_i$. What is the orientation of $\pi_i(C)$ here?
 - How to adjust the formula in b. when some projections are not bijective? (e.g. how to convert $\int_{S^1} \vec{F} \cdot d\vec{C}$ into $\int(\dots)dx + \int(\dots)dy$?) Using this formula recompute the integrals in part a.
 - Let M be a one-dimensional manifold and assume $\int_M \omega$ exists. For a finite subset $S \subset M$ prove: $\int_M \omega = \int_{M \setminus S} \omega$.
 - Take a neighborhood $S^1 \subset \mathcal{U} \subset \mathbb{R}^2$ and a function $f \in C^1(\mathcal{U})$. Define $\omega = df|_{S^1} \in \Omega^1(S^1)$. Compute $\int_{S^1} \omega$.
- Prove: $V_1 \otimes \dots \otimes V_k = 0$ iff at least one of V_j is a zero vector space.
 - Establish the natural (basis-free) isomorphisms:
 - $V_1 \otimes (V_2 \otimes V_3) \cong (V_1 \otimes V_2) \otimes V_3$.
 - $V \otimes (U \oplus W) \cong (V \otimes U) \oplus (V \otimes W)$.
 - $V^* \otimes W^* \cong (V \otimes W)^* \cong \text{Hom}(V, W^*) \cong \text{Hom}(W, V^*)$.
 - Fix some bases: $V = \text{Span}\{v_i\}$, $W = \text{Span}\{w_i\}$.
 - Prove: $\{v_i \otimes w_j\}$ is a basis of $V \otimes W$. (The non-trivial part here is the linear independence. Hint: use the dual bases of V^* , W^* .)
 - Write explicit bases for $\text{Sym}^k V^*$, $\wedge^k V^*$. (Verify that these are bases.)
 - Prove: the (skew-)symmetrization operations $\text{Sym} : \otimes^k V \rightarrow \otimes^k V$, $\text{Alt} : \otimes^k V \rightarrow \otimes^k V$ are projectors. In particular they result in (skew-)symmetric forms.
 - Prove:
 - $\text{Sym}(f \otimes g) = \text{Sym}(f \otimes \text{Sym}(g)) = \text{Sym}(\text{Sym}(f) \otimes g)$.
 - $\text{Alt}(f \otimes g) = \text{Alt}(f \otimes \text{Alt}(g)) = \text{Alt}(\text{Alt}(f) \otimes g)$.
 - For some vectors $\{v_i\}$ in V prove: $v_1 \wedge \dots \wedge v_k = 0$ iff these vectors are linearly dependent.
 - Verify: $f \wedge f = 0$ for any $f \in \wedge^k V^*$ with k -odd.
 - Given $f_i \in \wedge^{k_i} V^*$, verify: $f_1 \wedge \dots \wedge f_k = \frac{(k_1 + \dots + k_f)!}{k_1! \dots k_f!} \text{Alt}(f_1 \otimes \dots \otimes f_k)$.