

Ordinary differential equations for Math

(201.1.0061. Spring 2023. Dmitry Kerner)

Homework 6. Submission date: 7.05.2023

Questions to submit: 1. 2.b. 2.e. 2.f. 3.b. 3.f. 5.a.b.c.

Homeworks must be either typed (e.g. in Latex) or written in readable handwriting and scanned in readable resolution.



1. Prove: if $A \in Mat_{n \times n}(\mathbb{R})$ is \mathbb{C} -diagonalizable then A is \mathbb{R} -conjugate to a (real) block-diagonal matrix, with blocks of size ≤ 2 . Moreover, each 2×2 block can be brought to the form: $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$.
(Hint: the non-real eigenvectors of A come in conjugate pairs.
But we want a real basis, ...)

2. a. Prove: the functions $A = \sqrt{\text{trace}(\bar{A}^t \cdot A)}$, $\|A\|_{op} := \sup_{\|v\| \neq 0} \frac{\|Av\|}{\|v\|}$ define norms on $Mat_{n \times n}(\mathbb{R})$ and $Mat_{n \times n}(\mathbb{C})$. Moreover, $\|A \cdot B\|_{op} \leq \|A\|_{op} \cdot \|B\|_{op}$.

b. Disprove: i. $\|A\|_{op}$ equals the largest eigenvalue of A .

ii. The norm $\|*\|_{op}$ is conjugation-invariant (i.e. $\|A\|_{op} = \|UAU^{-1}\|_{op}$.)

c. Prove: the norms $\|*\|$, $\|*\|_{op}$ are equivalent. Prove: these normed spaces are complete.

d. Review questions 7,8 of homework.0

e. Prove: if $e^{At}e^{Bt} = e^{(A+B)t}$ holds for all $t \in (-\epsilon, \epsilon)$ then $AB = BA$.

f. Prove: if $e^A = \mathbb{I}$ then A is \mathbb{C} -diagonalizable. What are the possible eigenvalues?

3. a. Take the unit ball $Ball_1(\mathbb{O})_{op} := \{A \mid \|A\|_{op} < 1\} \subset Mat_{n \times n}(\mathbb{C})$.

Prove: if $A \in Ball_1(\mathbb{O})_{op}$ then $\mathbb{I} + A \in GL(n, \mathbb{C})$.

b. For a matrix $A \in Ball_1(\mathbb{O})_{op}$ define $\ln(\mathbb{I} + A) := \sum_{k=1}^{\infty} \frac{(-1)^{k+1} A^k}{k}$. Prove: the series converges absolutely, and the convergence is uniform on compact subsets of $Ball_1(\mathbb{O})_{op}$.

c. Prove: $\exp(\ln(\mathbb{I} + A)) = \mathbb{I} + A = \ln(e^{\mathbb{I} + A})$ for every $A \in Ball_1(\mathbb{O})$. (No long computations are needed here.)

d. Take the subset $Mat_{2 \times 2}(\mathbb{C}) \supset \Sigma := \{A \mid e^A = \mathbb{I}, \det(t\mathbb{I} - A) = t^2 + 4\pi^2\}$. Identifying $Mat_{2 \times 2}(\mathbb{C}) \cong \mathbb{C}^4$ prove: Σ is defined by one linear and one quadratic equation. (Hint: observe that any matrix in Σ must be diagonalizable.)

Conclude: Σ contains a two-parametric family of matrices. (Therefore, while the map \exp is locally invertible near 0, it is highly non-injective globally.)

e. Prove: if $AB = BA$ and $A, B, A + B + AB \in Ball_1(\mathbb{O})_{op}$ then $\ln[(\mathbb{I} + A)(\mathbb{I} + B)] = \ln(\mathbb{I} + A) + \ln(\mathbb{I} + B)$. In particular, $\ln[(\mathbb{I} + A)^k] = k \cdot \ln(\mathbb{I} + A)$ for every $k \in \mathbb{Z}$.

f. Compute $\frac{d}{dt} \ln(\mathbb{I} + At)$. (Do this in two ways, as we did for $\frac{d}{dt} e^{At}$ in the lecture.)

4. Define the functions $Mat_{n \times n}(\mathbb{C}) \xrightarrow{\sin, \cos} Mat_{n \times n}(\mathbb{C})$ via the Taylor expansion of \sin, \cos . Prove:

a. These series converge absolutely, the convergence is uniform on bounded subsets of $Mat_{n \times n}(\mathbb{C})$.

b. Prove: $e^{iA} = \cos(A) + i \cdot \sin(A)$. $\cos(A) = \frac{e^{iA} + e^{-iA}}{2}$. $\sin(A) = \frac{e^{iA} - e^{-iA}}{2i}$.

c. Prove: $\sin^2(A) + \cos^2(A) = \mathbb{I}$. If $AB = BA$ then $\sin(A+B) = \dots$, $\cos(A+B) = \dots$.

d. Compute $\frac{d}{dt} \cos(At)$ and $\frac{d}{dt} \sin(At)$. (Do this in two ways, as we did for $\frac{d}{dt} e^{At}$ in the lecture.)

5. In the following cases (without solving the equations):

i. Identify the equilibria points. When are these points (un)stable nodes/saddles?

ii. For which λ are there (un)bounded/periodic solutions?

iii. For the cases a. and b. draw the phase portraits.

Now write down the general (real) solutions, and verify the previously obtained properties.

a. $x' = y$, $y' = \lambda \cdot x$. (Distinguish between the cases $\lambda > 0$, $\lambda < 0$.)

b. $x' = \lambda x + y$, $y' = \lambda y$.

c. $\underline{x}' = A \cdot \underline{x}$ for $A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 1 & -1 \\ 2 & -1 & 0 \end{bmatrix}$.