

# Geometric Calculus 2, 201.1.1041

## Homework 13

Spring 2025 (D.Kerner)

Not for submission.



1. (For  $1 \leq r \leq \infty$ ) Take a smooth orientable hypersurface  $X \subset \mathbb{R}^{n+1}$ . Prove:  $X$  can be (globally!) defined by  $f(x) = 0$ , where  $f$  has no critical points on  $X$ .
  
  2. Let  $\mathcal{U} \subseteq \mathbb{R}^n$ . Define the maps:  $C^{r-1}(\mathcal{U}) \xrightarrow{\psi_n} \Omega^n(\mathcal{U})$ , by  $f \rightarrow \omega_f^n := f \cdot dx_1 \wedge \cdots \wedge dx_n$ ,  
 $\{\text{vector fields on } \mathcal{U}\} \xrightarrow{\psi_{n-1}} \Omega^{n-1}(\mathcal{U})$ , by  $\vec{F} \rightarrow \omega_{\vec{F}}^{n-1} := (dx_1 \wedge \cdots \wedge dx_n)(\vec{F})$ ,  
and  $\{\text{vector fields on } \mathcal{U}\} \xrightarrow{\psi_1} \Omega^1(\mathcal{U})$ , by  $\vec{F} \rightarrow \omega_{\vec{F}}^1 := \sum F_i \cdot dx_i$ .
    - a. Verify: these are  $C^{r-1}(\mathcal{U})$ -linear isomorphisms. Verify:  $\omega_{grad(f)}^1 = df$  and  $\omega_{\vec{F}}^{n-1} \wedge \omega_{\vec{G}}^1 = \omega_{\vec{F} \cdot \vec{G}}^n$ .
    - b. Specify bases (of the source and the target) for which  $[\psi_1] = \mathbb{I}$ , and  $[\psi_{n-1}] = \mathbb{I}$ .
    - c. The classical “divergence operator” is defined via the identity  $\omega_{div(\vec{F})}^n = d\omega_{\vec{F}}^{n-1}$ .  
Verify:  $div(\vec{F}) = \nabla \cdot \vec{F}$ . (The scalar product.)
    - d. For  $\mathcal{U} \subseteq \mathbb{R}^3$  the vector product can be defined via  $\omega_{\vec{F} \times \vec{G}}^2 = \omega_{\vec{F}}^1 \wedge \omega_{\vec{G}}^1$ . Write  $\vec{F} \times \vec{G}$  explicitly.  
The classical “rotor operator” is defined via  $\omega_{rot(\vec{F})}^2 = d\omega_{\vec{F}}^1$ . Verify:  $rot(\vec{F}) = \nabla \times \vec{F}$ , the vector product.
  
  3. a. Take a smooth hypersurface-germ  $(X, p) \subset (\mathbb{R}^{n+1}, p)$ . Fix some linearly independent vectors  $v_1 \dots v_n \in T_{(X,p)}$ . Define the 1-form  $\omega_{v_1 \dots v_n} \in T_{(\mathbb{R}^{n+1}, p)}^*$  by  $\omega_{v_1 \dots v_n}(v) = det[v_1, \dots, v_n, v]$ . For the map  $\psi_1$  of question 2 prove:  $(\psi_1)^{-1}\omega_{v_1 \dots v_n}$  is the normal  $\vec{n}_p$  to  $X$  at  $p$ .
    - b. Given a function  $\mathbb{R}^n \supset \mathcal{U} \xrightarrow{f} \mathbb{R}$ , take its graph  $\Gamma_f \subset \mathcal{U} \times \mathbb{R}^1$ . Take the upper normal to  $\Gamma_f$ , i.e.  $\hat{n} \cdot \hat{y} > 0$ , and the corresponding orientation of  $\Gamma_f$ .
      - i. What is the corresponding orientation on  $\mathcal{U}$ ?
      - ii. Given a vector field  $\vec{F}$  on  $\mathcal{U} \times \mathbb{R}^1$ , prove: its flux through  $\Gamma_f$  is  $\int_{\mathcal{U}} (\vec{F} \cdot (-\nabla_u f, 1))|_{\Gamma_f} \cdot du_1 \cdots du_n$ .
    - c. Take  $S^2 \subset \mathbb{R}^3$ , with the outer normal. (What is the corresponding order of  $\theta, \phi$ ?)
      - i. Prove: the flux of the field  $\vec{F} = f \cdot \vec{r}$  through  $S^2$  equals to  $\iint_S \vec{F} d\vec{S} = \iint_{\theta, \phi} f \cdot r^3 \sin(\theta) d\theta d\phi$ .
      - ii. Compute the flux of  $\vec{F} = \frac{\vec{r}}{r^d}$  through  $S^2 \subset \mathbb{R}^3$ .
  
  4. a. Take a smooth hypersurface  $X \subset \mathbb{R}^{n+1}$  with a chosen normal  $\hat{n}$ . Project onto coordinate hyperplanes,  $\mathbb{R}^{n+1} \subset X \xrightarrow{\pi_i} \mathbb{R}^n = \{x_i = 0\}$ . Denote the images  $\mathcal{U}_i := \pi_i(X)$ . Suppose each  $\pi_i$  is invertible and (outside of a set of  $dim \leq n-1$ ) the inverse map  $\pi_i^{-1} : \mathcal{U}_i \rightarrow X$  is a parametrization.  
Prove: the flux of a vector field  $\vec{F}$  through  $X$  equals to  $\sum_i \int_{\mathcal{U}_i} sign(n_i) \cdot (F_i \circ \pi_i^{-1}) \cdot du_1^i \cdots du_n^i$ .
    - b. Let  $X = \partial \bar{\mathcal{U}} \subset \mathbb{R}^{n+1}$ , where  $\bar{\mathcal{U}}$  is a convex bounded set. Suppose each  $F_i$  is independent of  $x_i$ .  
Prove: the total flux of  $\vec{F}$  through  $X$  is zero.
    - c. Take  $S = (\partial Pyramid) \setminus \mathcal{U}$ , with  $Pyramid \subset \mathbb{R}^3$  defined by  $x, y, z \geq 0, x + y + z \leq 1$ , and  $\mathcal{U} \subset \mathbb{R}_{xy}^2$  is defined by  $x, y \geq 0, x^2 + y^2 \leq \frac{1}{2}$ . (The orientation corresponds to the outer normal.)  
Compute  $\int_S \omega$ , where  $\omega = (x+z)dx \wedge dy + (z+y+\cos(x))dy \wedge dz + (x-\sin(y))dz \wedge dx|_S$ .
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5. a. Compute  $\int_C \vec{F} d\vec{C}$  in the following cases:
  - i.  $\vec{F} = \frac{(-y, x)}{x^2+y^2}, C = \{x^2 + y^2 = 1\} \subset \mathbb{R}^2$  (counterclockwise).
  - ii.  $\vec{F} = \frac{(-y, x)}{x^2+y^2}$ , and the curve  $(\sqrt{3}, 1) \rightsquigarrow (-\sqrt{3}, 1)$  is given in polar coordinates by  $r(\theta) = \frac{1}{1-\sin(\theta)}$ .
  - b. For each  $n \in \mathbb{N}$  give a closed oriented curve that does not pass through  $(0, 0)$  and satisfies:  $\oint_C \frac{(-y, x)}{x^2+y^2} d\vec{C} = 2\pi n$ .
  - c. Find the smooth, closed oriented curve  $C$  for which the integral  $\oint_C (\frac{x^2 y}{4} + \frac{y^3}{3}) dx + x dy$  achieves maximum.
  - d. Take a compact  $\bar{\mathcal{U}} \subset \mathbb{R}^2$ , suppose  $\partial \bar{\mathcal{U}}$  is piecewise smooth. Take the outer orientation. Prove:  $vol_2(\bar{\mathcal{U}}) = \oint_{\partial \bar{\mathcal{U}}} x dy = - \oint_{\partial \bar{\mathcal{U}}} y dx$ . Compute the area bounded by the curve  $|\frac{x}{a}|^{\frac{2}{p}} + |\frac{y}{b}|^{\frac{2}{p}} = 1$ .