

Geometric Calculus 2

201.1.1041 Spring 2025 (D.Kerner)

Homework 9.

Submission date: 2.06.2025.

Questions to submit: 1.e. 1.f. 2.a. 2.c.ii. 3.a. 3.d. 4.a.ii. 4.b. 4.d. 4.e.

(Either typed or in readable handwriting and scanned in readable resolution.)



1. Fix a germ of manifold $(X, x_o) \subset (\mathbb{R}^N, x_o)$. Its normal space is $\mathcal{N}_{(X, x_o)} := (T_{(X, x_o)})^\perp \subset T_{(\mathbb{R}^N, x_o)}$, the orthogonal complement for the standard inner product on $T_{(\mathbb{R}^N, x_o)} = \mathbb{R}_v^N$.
 - a. For a hypersurface-germ $(X, x_o) = \{f(x) = 0\} \subset (\mathbb{R}^{n+1}, x_o)$, with $\nabla f|_{x_o} \neq 0$, prove: $\mathcal{N}_{(X, x_o)} = \text{Span}(\nabla f|_{x_o})$.
 - b. Extend a. to the case of several equations.
 - c. (Dis)prove: $\dim[\mathcal{N}_{(X, x_o)}]$ depends only on the diffeomorphism type of (X, x_o) , and not on the embedding $(X, x_o) \subset (\mathbb{R}^N, x_o)$.
 - d. (Dis)prove: every map $(X, x_o) \xrightarrow{\phi} (Y, y_o)$ induces either $\mathcal{N}_{(X, x_o)} \xrightarrow{\phi^*} \mathcal{N}_{(Y, y_o)}$ or $\mathcal{N}_{(X, x_o)} \xleftarrow{\phi^*} \mathcal{N}_{(Y, y_o)}$.
 - e. The decomposition $T_{(X, x_o)} \oplus \mathcal{N}_{(X, x_o)} = T_{(\mathbb{R}^N, x_o)}$ implies $T_{(X, x_o)}^* \oplus \mathcal{N}_{(X, x_o)}^* = T_{(\mathbb{R}^N, x_o)}^* = (\mathbb{R}_v^N)^*$.
Using it verify: $T_{(X, x_o)}^* = \{l \in (\mathbb{R}_v^N)^* \mid l(\mathcal{N}_{(X, x_o)}) = 0\}$. And accordingly: $T^*X = \{\dots??\dots\} \subset T^*\mathbb{R}^N$.
 - f. Prove: any element of $T_{(X, x_o)}^*$ is presentable as $df|_{x_o}$ for a function $(X, x_o) \xrightarrow{f} \mathbb{R}^1$.
 - g. (Dis)prove: every map $(X, x_o) \xrightarrow{\phi} (Y, y_o)$ induces $T^*X \xleftarrow{\phi^*} T^*Y$.

2. a. Express the forms $dx, dy, dz \in \Omega^1(\mathbb{R}^3)$ in polar coordinates. Express the forms $dr, d\theta, d\phi$ in cartesian coordinates.
b. Take the standard Torus $\subset \mathbb{R}^3$. Take $\omega = \sum \omega_i dx_i \in \Omega^1(\mathbb{R}^3)$. Present the restriction $\omega|_{\text{Torus}}$ in the coordinates (ϕ, ψ) on this torus.
c. Take a map of manifolds $X \xrightarrow{\phi} Y$ and the corresponding pullback $\Omega^1(X) \xleftarrow{\phi^*} \Omega^1(Y)$.
 - i. Verify: $\phi^*(f \cdot \omega) = \phi^*(f) \cdot \phi^*(\omega)$.
 - ii. Verify: $\phi^*df = d\phi^*f$. In particular, for a submanifold $X \subseteq Y$ one has $(df)|_X = d(f|_X)$.
 - iii. For two maps $X \xrightarrow{\phi} Y \xrightarrow{\psi} Z$ verify the chain rule: $T_{(X, x_o)}^* \xleftarrow{(\psi \circ \phi)^* = \phi^* \circ \psi^*} T_{(Z, z_o)}^*$ and $\Omega^1(X) \xleftarrow{(\psi \circ \phi)^* = \phi^* \circ \psi^*} \Omega^1(Z)$.

3. a. Take a function $f \in C^r(\mathcal{U})$ for an open $\mathcal{U} \subseteq \mathbb{R}^n$. Define $\omega = df$ and $\xi = \text{grad}(f)$. Compute $\omega(\xi)$.
b. Verify: the pairing of 1-forms and vector fields, $(\omega, \xi) \rightarrow \omega(\xi)$, is $C^r(X)$ -bilinear, i.e. $\omega(\xi_1 + \xi_2) = \dots$, $\omega(f \cdot \xi) = f \cdot (\omega(\xi)) = (f \cdot \omega)(\xi)$, $(\omega_1 + \omega_2)\xi = \dots$.
c. We have defined the map $C^r(X) \rightarrow \Omega^1(X)$, $f \rightarrow df$. Verify: it is \mathbb{R} -linear, and satisfies the Leibniz rule.
d. A submanifold $X \subset \mathbb{R}^{n+1}$ is defined by the equation $f(\underline{x}) = 0$ for some $f \in C^r(\mathbb{R}^N)$. Compute $df|_X$.

4. a. Compute $\int_C \vec{F} \cdot d\vec{C}$ in the following cases:
 - i. $\vec{F}(\underline{x}) = (x_1, x_2^2, \dots, x_n^n)$, $\vec{C} = \{(\sin(t), \sin^2(t), \dots, \sin^n(t)) \mid t \in [0, \pi]\}$.
 - ii. $\int_{\left\{ \begin{array}{l} z^2 dx + 3y^2 dy - x^2 dz \\ y = -x, z > 0 \end{array} \right\}} (z^2 dx + 3y^2 dy - x^2 dz)$, the curve begins at $(\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}, 0)$ and ends at $(\frac{-1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0)$.
b. Given a smooth curve $C \subset \mathbb{R}^n$, take the projections onto the coordinate axes $\{C \xrightarrow{\pi_i} \text{Span}(\hat{x}_i)\}$. Suppose these are diffeomorphisms onto their images. Prove: $\int_C \vec{F} \cdot \vec{C} = \sum \int_{\pi_i(C)} F_i(\pi_i^{-1}(x_i)) dx_i$. What are the orientations of $\pi_i(C)$ here?
c. How to adjust the formula in b. when some projections are not bijective? (e.g. how to convert $\int_{S^1} \vec{F} \cdot d\vec{C}$ into $\int(\dots)dx + \int(\dots)dy$?) Using this formula recompute the integrals in part a.
d. (Newton-Leibniz) Take a parameterized oriented curve $\mathbb{R}^1 \supset (a, b) \xrightarrow{\phi} C \subset \mathbb{R}^N$ and $\omega = df \in \Omega^1(C)$.
Verify: $\int_{\vec{C}} \omega = f(\phi(b)) - f(\phi(a))$.
e. Take a smooth oriented curve $S^1 \cong C \subset \mathbb{R}^N$. Prove: $\int df = 0$ for any $f \in C^1(C)$.